



PHINS, an all-in-one sensor for DP applications

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INTRODUCTION

- ▶ Positioning sensor is one of the key elements of DP systems
- ▶ DGPS is a great positioning system but it may be subject to some interruptions in service:
 - Scintillation effects
 - Signal masking
 - Multipath

INTRODUCTION

- ▶ Continuity, integrity and availability are the characteristics needed for the positioning reference system.
- ▶ Complementing DGPS with additional sensors is a solution:
 - PHINS, an inertial navigation system
 - GAPS a compact, portable calibration free acoustic position system

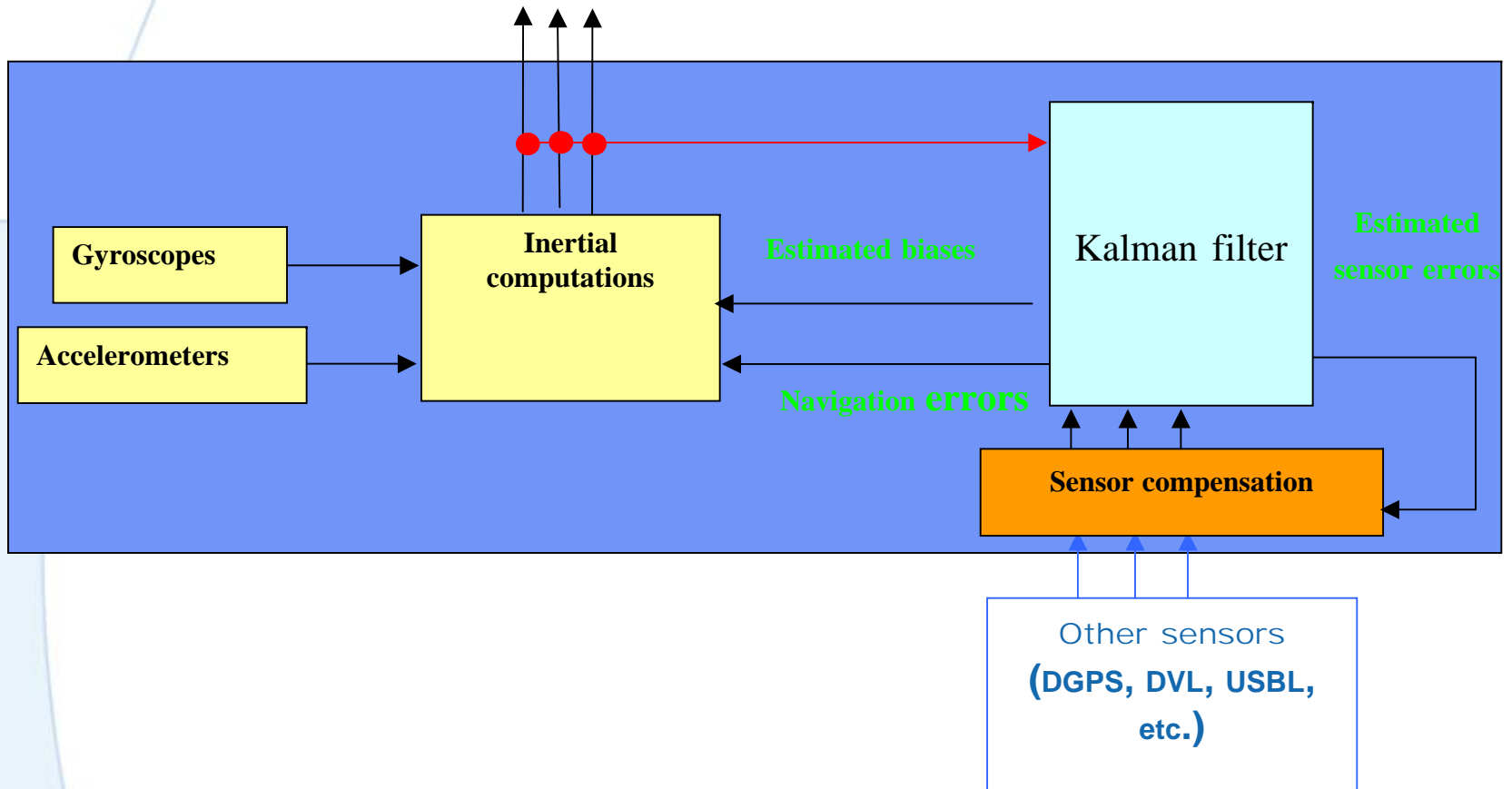
PHINS, a Fiber Gyro Navigation System



- ▶ Small, light
- ▶ Provides :
 - Position
 - Roll, Pitch
 - Heading
 - Heave, Altitude
 - Rate of turn

PHINS

Attitude, positions, speeds



PHINS

GPS data



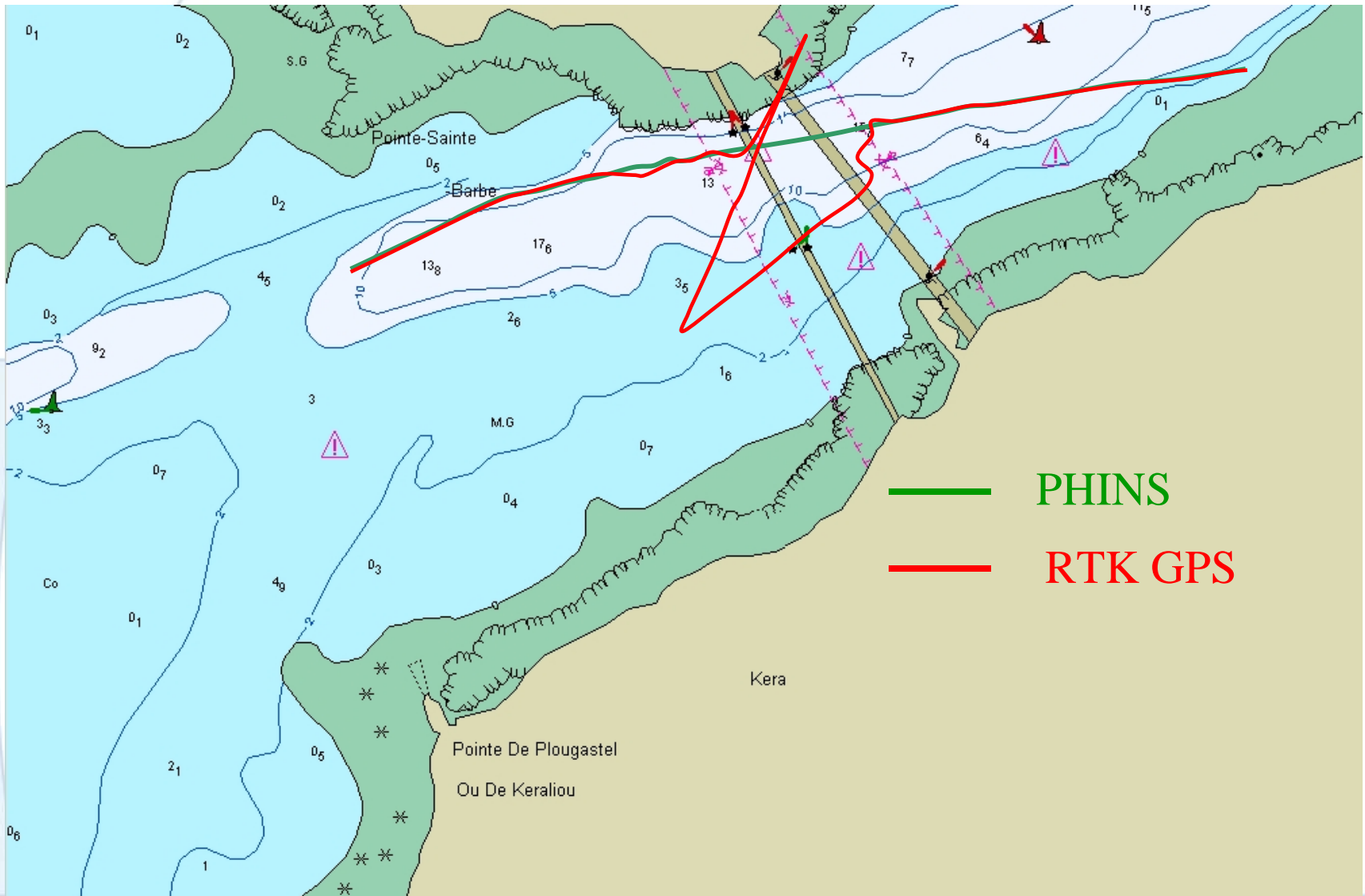
DVL data



USBL data



Optimal
Position
data



PHINS

~~GPS data~~

DVL data

USBL data



Optimal
Position
data

PHINS TEST RESULTS

Phins #27 _ Test # 22
Position error (DVL aiding)



PHINS

~~GPS data~~

~~DVL data~~

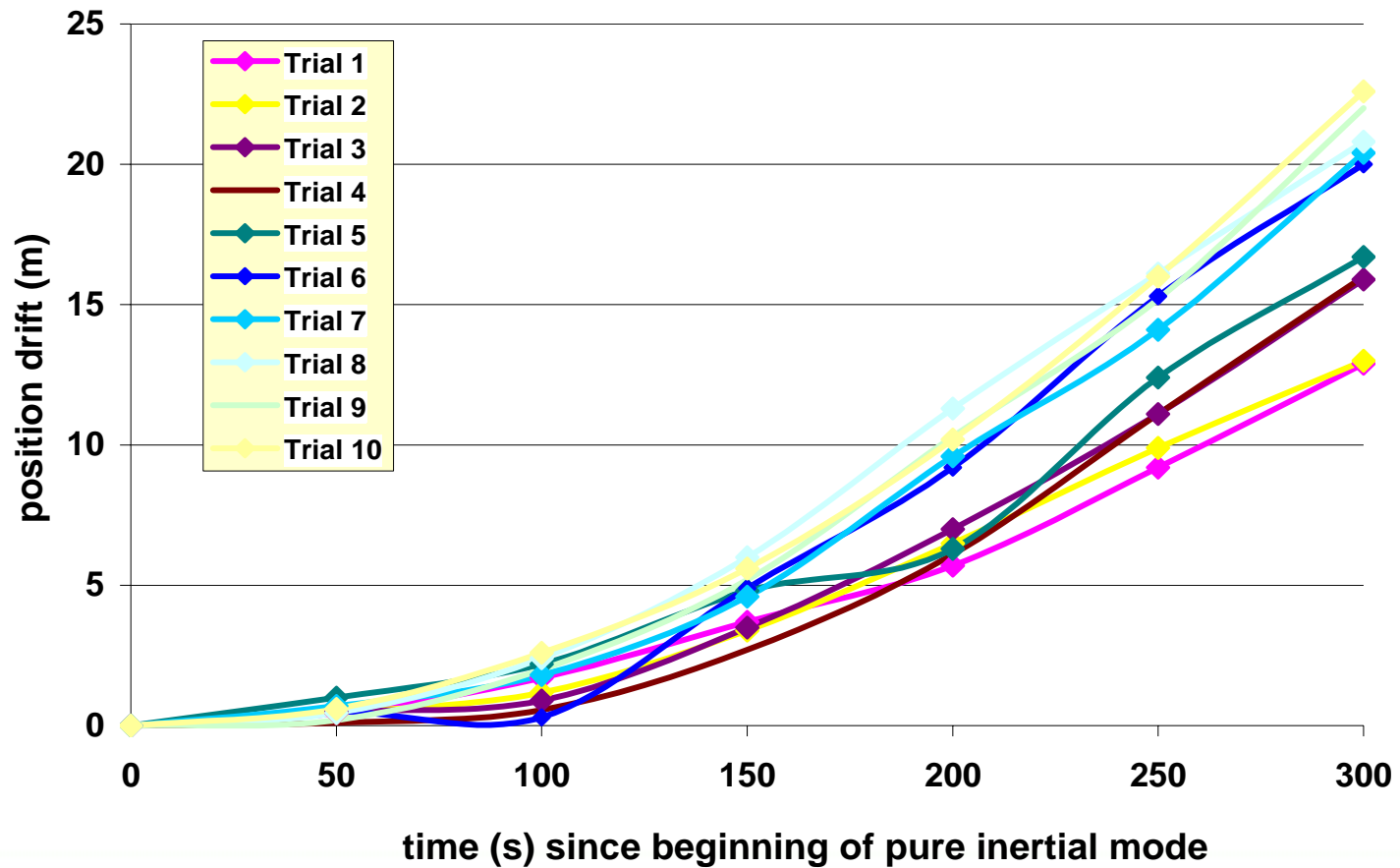
~~USBL data~~



Optimal
Position
data

PHINS test results

Position drift in pure inertial mode (no GPS aiding, no DVL aiding)



PHINS

DGPS 1

DGPS 2

DVL

USBL

PHINS

DP
Control system

DGPS like
interface



PHINS

- ▶ Detects and rejects any DGPS position jump
- ▶ Able to maintain 2 meter accuracy for one hour with DVL aiding
- ▶ Can use USBL data and no GPS at all for eliminating common mode errors
- ▶ Provides data at high rate (up to 100 Hz)

GAPS



- ▶ USBL :
- ▶ Contains :
 - 3D acoustic antenna
 - Broadband signal processing
 - FOG based navigation system
 - Kalman filter

GAPS

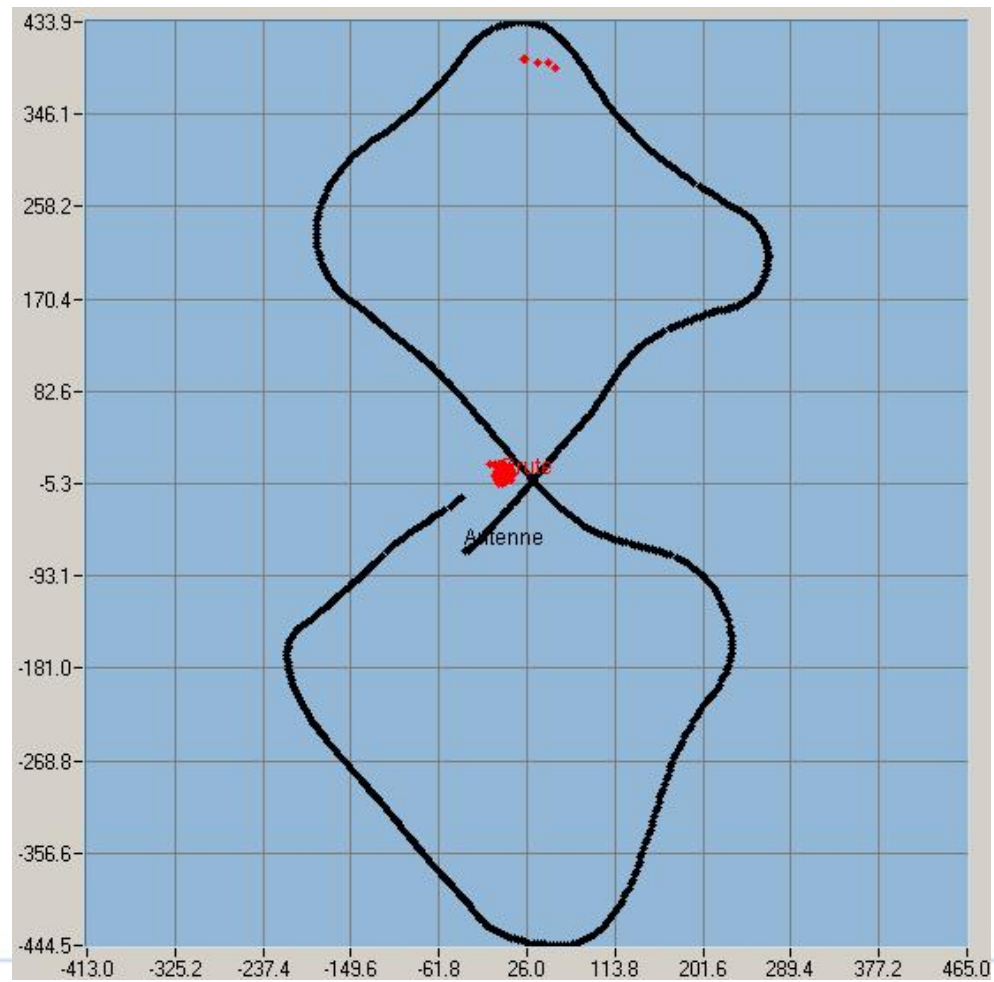
- ▶ Single, minimally sized housing
- ▶ Free of calibration
- ▶ Improved accuracy and higher acoustic position update rate
- ▶ Short time update of subsea positions during acoustic drop-out
- ▶ Complete acoustic coverage with tracking close to surface
- ▶ Robust to GPS outage
- ▶ Cost savings and outstanding value-for-money for hardware and performance



GAPS

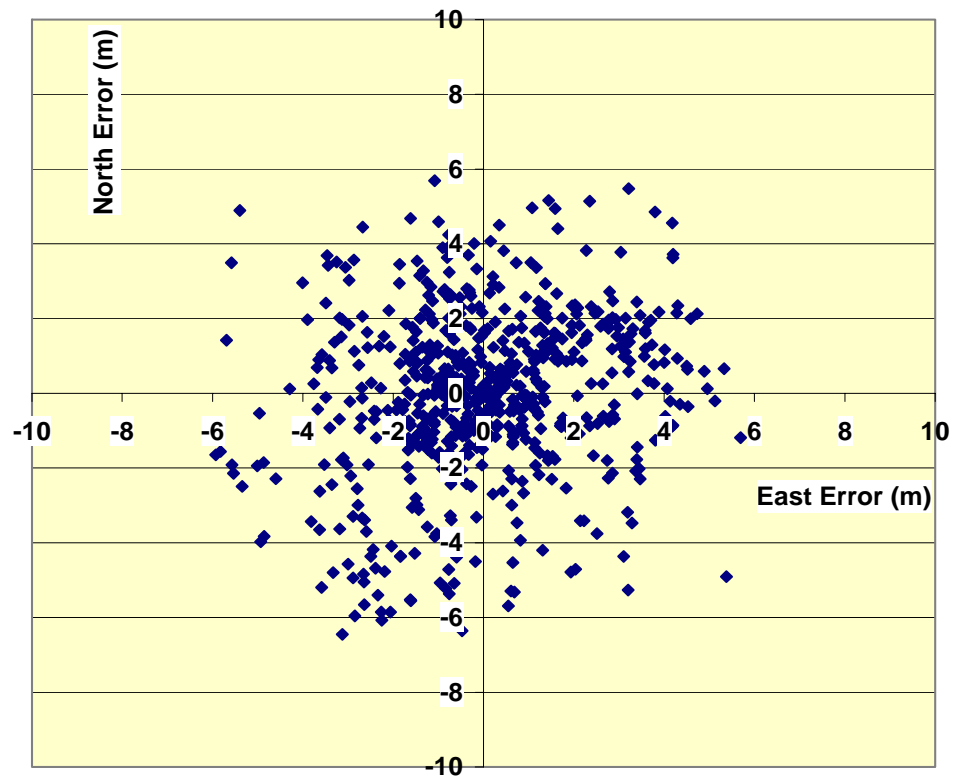
- ▶ Operates in the 19-30 KHz frequency range
- ▶ 4000 meters range
- ▶ Accuracy : 0.2 % of slant range

GAPS TESTS RESULTS



GAPS TEST RESULTS

GAPS : Transponder Position Error



GAPS USE

- ▶ The beacon is moored
- ▶ While DGPS is available, GAPS computes automatically beacon position
- ▶ When DGPS no more available, GAPS computes vessel position using beacon position and acousti measurements.

CONCLUSION

- ▶ PHINS and GAPS are alternative sensors that would allow enhancing

- Integrity
- Availability
- Redundancy

of DP positioning reference systems